The Role of Rapid Changes in Weather on Phytoplankton Spring Bloom Dynamics Captured by an Autonomous Uncrewed Surface Vehicle

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Abstract

The spring phytoplankton bloom plays a major role in pelagic ecosystems; however, its dynamics is overlooked due to insufficient, highly-resolved observational data. Here we investigate the start, peak and decline of a two-week phytoplankton spring bloom in Frohavet, located at the coast of mid-Norway. We used observations from an uncrewed surface vehicle (USV) combined with buoy measurements, satellite images, discrete water sampling and modelling approaches. The spring bloom (March-June 2022) consisted of multiple peaks (up to 5 mg m\textsuperscript{-3}), with a long peak in April, coincident with the period when the USV captured the temporal and spatial dynamics of the bloom. Short-term (5 days) episode of calm weather in the spring, such as clear skies and consistent low wind speed ($< 7$ m s\textsuperscript{-1}) shoaled the mixed layer depth ($< 15$ m), after strong wind speed (average wind speed up to 20 m s\textsuperscript{-1} in March) and mixing events in winter. These rapid changes in the environment promoted the rapid development of the spring bloom - from 1 to 5 mg m\textsuperscript{-3} in 5 days. Likewise, the collapse of the bloom was rather quick, 1-2 days and coincides with low nitrate values and rapid increase in wind speed ($> 10$ m s\textsuperscript{-1}), suggesting strong influence of the environment on phytoplankton dynamics during early stages of the spring bloom. Understanding the dynamics of the spring bloom is crucial for the management of marine resources. Integration of distinct observational platforms has the potential to unveil the environmental factors underlying phytoplankton bloom dynamics.
[The role of rapid changes in weather on phytoplankton spring bloom dynamics captured by an autonomous uncrewed surface vehicle]

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Table S1. Abundance (cell mL⁻¹) of the ten most dominant phytoplankton taxa from the fixed buoy station near Frøya island (Figure 1).

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<th>22 Feb</th>
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<th>06 Apr</th>
<th>18 Apr</th>
<th>04 May</th>
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<td>0</td>
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1
The Role of Rapid Changes in Weather on Phytoplankton Spring Bloom Dynamics
Captured by an Autonomous Uncrewed Surface Vehicle

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Key Points:

• The spring bloom in coastal high latitudinal regions consisted of multiple peaks
  associated with gain and loss processes.
• Relaxation of strong winds and clear skies for 7-10 days in spring allowed phytoplankton
  accumulation and bloom development.
• Episodic strong winds interluded spring bloom development after a period of calm, sunny
  weather.
Abstract

The spring phytoplankton bloom plays a major role in pelagic ecosystems; however, its dynamics is overlooked due to insufficient, highly-resolved observational data. Here we investigate the start, peak and decline of a two-week phytoplankton spring bloom in Frohavet, located at the coast of mid-Norway. We used observations from an uncrewed surface vehicle (USV) combined with buoy measurements, satellite images, discrete water sampling and modelling approaches. The spring bloom (March-June 2022) consisted of multiple peaks (up to 5 mg m\(^{-3}\)), with a long peak in April, coincident with the period when the USV captured the temporal and spatial dynamics of the bloom. Short-term (5 days) episode of calm weather in the spring, such as clear skies and consistent low wind speed (< 7 m s\(^{-1}\)) shoaled the mixed layer depth (< 15 m), after strong wind speed (average wind speed up to 20 m s\(^{-1}\) in March) and mixing events in winter. These rapid changes in the environment promoted the rapid development of the spring bloom - from 1 to 5 mg m\(^{-3}\) in 5 days. Likewise, the collapse of the bloom was rather quick, 1-2 days and coincides with low nitrate values and rapid increase in wind speed (> 10 m s\(^{-1}\)), suggesting strong influence of the environment on phytoplankton dynamics during early stages of the spring bloom. Understanding the dynamics of the spring bloom is crucial for the management of marine resources. Integration of distinct observational platforms has the potential to unveil the environmental factors underlying phytoplankton bloom dynamics.
Plain Language Summary

The phytoplankton spring bloom is an important recurrent phenomenon because it provides food for the marine food web and regulates the climate. Although previous studies were focused on the initiation of the spring bloom, its dynamics, meaning, rapid changes in formation and decline, are usually not observed in detail. Here we used a combination of a technological (marine sensors and robots) and traditional methods (water collection, laboratorial and microscopic analyses) to observe the spatial and temporal variation of the spring bloom in a biological hotspot of the coast of mid-Norway. Small windows of ‘good weather’, where few days of sunny, clear skies and weak winds in the midst of ‘stormy spring’ promoted the rapid development of the spring bloom dominated by the diatom Skeletonema. The bloom collapsed after the wind speed got high again, suggesting the strong influence of environmental conditions in the spring bloom. Here we demonstrated that the use of multiple ocean observation platforms is crucial to understand, in detail, the processes controlling the spring phytoplankton bloom.

Index terms

4855 Phytoplankton 4894 Instruments, sensors, and techniques 4271 Physical and chemical properties of seawater

Keywords: phytoplankton dynamics, environmental controls, phytoplankton spring bloom, non-photochemical quenching, uncrewed surface vehicles.
1 Introduction

The spring phytoplankton bloom is a key event in the annual cycle of phytoplankton abundance in high latitudinal seas (Chiswell et al., 2014; Rumyantseva et al., 2019). As a recurrent seasonal phenomenon, the spring bloom plays a major role in pelagic ecosystems, contributing to carbon export and sequestration, oxygen production and energy flow for higher trophic levels (Alkire et al., 2014). Phytoplankton spring bloom are also sentinels of climate change, where alterations in intensity and phenology have been observed (Edwards & Richardson, 2004), with predictions of a continuous shift by the end of the century (Henson et al., 2018; Yamaguchi et al., 2022).

In simple terms, phytoplankton spring blooms consist of positive biomass accumulation rate ($r$) over a period of time, where growth ($\mu$, e.g. cellular division) surpasses loss processes ($l$, e.g., grazing and sinking rates, viral lysis) ($r = \mu - l$, $r > 0$). While there is a scientific consensus that spring blooms consist of accumulation of phytoplankton, the processes that determine their start and the net balance between $\mu$ and $l$, are still on debate (Mojica et al., 2021). Moreover, there is also a debate of what constitute a bloom, whether accumulation is explosive (rapidly increase in $r$) or steadily increasing over time (Mignot et al., 2018). Historically, $r > 0$ in spring was viewed as a bottom-up process, where $l$ remained unchanged and $\mu$ increased rapidly as light becomes a non-limiting factor with shoaling of the mixed layer (Sverdrup, 1953). Recently, this hypothesis has been contested, where low $l$ due to low grazing rates as a consequence of low encounter rates of phytoplankton and zooplankton, rather than a fast change in $\mu$ in spring, would account for slow $r > 0$ in winter (Behrenfeld, 2010; Behrenfeld et al., 2013; Behrenfeld & Boss, 2014). These authors also suggested that tight recoupling between grazers and phytoplankton occur when the mixed layer start to become shallow, with a slight lag (1 day) in time, where $l$. 
the deterministic factor for \( r > 0 \), would eventually catch up with \( \mu \) after an early stock of phytoplankton biomass in winter (Behrenfeld & Boss, 2014).

The debate around spring bloom is mostly focused on their initial stage, although, in reality, these such blooms are quite dynamic in high latitudinal and polar seas (Behrenfeld et al., 2017). This means that weather changes (e.g. cloud cover, wind speed), particularly in spring, are rather fast (< 1 day), where the volatile nature of these blooms consists of multiple peaks with rapid formation and collapse over the course of few days or weeks. Thus, many studies ignore the influence of ‘small windows of good weather’, where few days of sunny, clear skies and weak winds during a ‘stormy spring’ might have a huge impact on phytoplankton dynamics.

Central to this problem is the lack of sufficient, highly-resolved observational data, particularly for regions that are highly dynamic and complex. For many years, spring blooms have been studied using satellites, which close progression of blooms are missed due to cloud cover often occurring in high latitudinal seas (Behrenfeld, 2010). Discrete water and net sampling over a long-term time series provides detailed information of plankton species (González-Gil et al., 2022); however, microscopic analyses are time-consuming and, in many times, not highly resolved in space and time. Fixed platforms, including buoys, can provide high temporal resolution (< 1h), however, spatial patchiness is often be missed (Son et al., 2014). Mobile platforms, including profiling floats (Boss & Behrenfeld, 2010; Mignot et al., 2018) and gliders (Rumyantseva et al., 2019) are suitable, but only for deep, open waters (> 200 m) due to the potential collision to a shallow seafloor. For coastal regions, with shallow and irregular bathymetry, autonomous uncrewed surface vehicles (USV) can offer an affordable, flexible solution for studying phytoplankton spring bloom progression, although observations comprise only surface waters (Dallolio et al., 2021; Scott et al., 2020). Modelling approaches can offer
complementary information regarding areas not covered by satellites and USVs and can also
provide the vertical structure of the water column. An “observational pyramid” for ocean
systems, which combines the integration of in-situ autonomous platforms, fixed buoys, satellite
imagery and modelling approaches with discrete net and water sampling have the capacity to
unveil the dynamics of a phytoplankton spring bloom in a coastal, productive hot-spots (Fragoso
et al., 2022; Williamson et al., 2023).

In-situ chlorophyll a fluorescence (FChla) measurements derived from sensors attached
to autonomous or fixed platforms have been historically used as a proxy of phytoplankton
biomass in studies of bloom dynamics (Roesler et al., 2017). However, FChla measurements are
only useful when they reflect the true concentration of chlorophyll a [Chla] in the water.
Systematic errors, such as biofouling and non-photochemical quenching (NPQ) influence the
fluorescence signal to intracellular Chla pigment ratios, offering biased measurements (Carberry
et al., 2019; Johnsen et al., 2018; Scott et al., 2020). NPQ is a physiological response of live cells
to high light (usually observed in surface waters at daytime), where the excess of energy is
converted to heat, reducing the FChla signal (Huot & Babin, 2010). Thus, it is crucial that, for
surface FChla measurements derived from USVs, values are corrected for NPQ, particularly
during spring and summer.

Here, we use an USV equipped with environmental and weather sensors (fluorometer,
CTD, oxygen optode and weather station) to investigate the dynamics (start, peak and decline) of
a 2-week phytoplankton spring bloom in Frohavet, a coastal Norwegian biological hotspot. To
complement the USV data (resolved to 1 min binned), a combination of other observational
methods, including a fixed mooring buoy, satellite images, discrete water sampling and
modelling approaches were included. For FChla from the USV, we provide a solution for NPQ
for daily changes and investigate the biophysical controls of the bloom. Discrete water samples
for nutrient concentrations and phytoplankton abundances, in addition to \( FChla \) measurements
from a moored buoy, were collected from a fixed station \( \sim25 \) km away from the trajectory of the
USV AutoNaut. Integration of distinct observational platforms, such as autonomous vehicles,
fixed buoys, discrete water sampling and modelling approaches has the potential to unveil the
environmental factors underlying phytoplankton bloom dynamics.

2 Materials and Methods

2.1 Study area

Frohavet is a wide, open stretch of sea surrounded by a large cluster of small islands on
the coast of Trøndelag, mid-Norway (Fig. 1). This region sustains high levels of primary
production and biological diversity and is a popular site for aquaculture activities. Frohavet is
highly productive because of the Norwegian Atlantic Water (NAW), which brings nutrient-rich
Atlantic Water (AW) along the shelf break. This water mass is located below the Norwegian
Coastal Current (NCC), which becomes thicker as freshwater input increases from spring to
summer (Fragoso et al., 2019). The NAW often reaches the surface through coastal upwelling
and internal waves (Fragoso et al., 2019). Diatoms are known to be the predominant
phytoplankton of the spring bloom (Fragoso et al 2021, Thu et al 2021), however, dinoflagellates
often to co-occur. Diatoms blooms sustains high zooplankton (particularly copepods) abundance(predominantly found in this region (Fragoso et al., 2019).
Figure 1 - Study site in the coast of mid-Norway. a) Scheme showing the main currents flowing northwards – the Norwegian Coastal Current (blue) and the Norwegian Atlantic Current (red). b) Map of Frohavet region showing the islands of Frøya and Hitra, in addition to the weather station in Sula Island (cross symbol), the fixed buoy station near Frøya (star symbol) and the site where mixed layer depth was modelled by SINMOD (circle symbol).

2.2 Buoy and water sampling

To monitor the start and development of the bloom in the region of Frohavet, a C3 submersible fluorometer sensor (Turner Designs, USA) was attached into a buoy located about 2 km east of the coast of Frøya Island (Fig. 1) and placed at 4 m depth (Fig. 1). This sensor collected temperature (°C), $FChla$ (calibrated later to concentration in mg m$^{-3}$) and turbidity (Relative Fluorescence Unit - calibrated later to Formazin Turbidity Unit (FTU)) every 10 min from mid-February to mid-June. Hourly wind speed (m s$^{-1}$) data (from February until mid-June) from Sula
meteorological station (located in the western part of Frohavet) were collected from the Norwegian Weather Service Center [https://seklima.met.no/]. A HOBO pendant temperature and light logger (HOBO, USA) was placed at the top of the buoy to measure light intensity in air (measurement in lux at every 30 min from February until June). Values were integrated daily and converted to photosynthetic active radiance (µmol photons m⁻² s⁻¹) by using a conversion factor:

1 klux (kilolux)= 14-18 µmol photons m⁻² s⁻¹ (Sakshaug et al., 2009).

Discrete water sampling for nitrate and in vitro chlorophyll concentrations ([Chla_in-vitro]) was collected at 3 m depth and every 2-3 weeks from mid-February to mid-June few meters away from where the C3 sensor was attached. For nitrate analyses, triplicate water samples were filtered with a 0.8 µm polycarbonate filter, where the filtrate water was immediately kept in a centrifuge tube and stored frozen at -20°C. Nitrate analyses were determined in the laboratory using a continuous flow automated analyzer (CFA, Auto-Analyzer 3, SEAL). For [Chla_in-vitro], seawater was filtered (0.25-0.5 L) onto a Whatman GF/F glass fiber filters, and immediately double-folded, wrapped in aluminum foil and stored at -20°C for a posteriori analyses in the laboratory. For a fluorometric determination of [Chla_in-vitro], frozen filters were placed in glass vials with 100% methanol for few hours on a dark fridge at 10°C. For [Chla_in-vitro], the extracted solvent was determined using the Turner Designs Trilogy fluorometer (model: 7200-000) and the non-acidification method (Fragoso et al., 2019). For phytoplankton identification and quantification, water samples were fixed with neutral Lugol’s iodine solution to a final concentration of ~1% into dark amber bottles and stored at room temperature and in the dark for later microscopic analyses in the laboratory.
2.3 USV AutoNaut sampling

The AutoNaut is a commercially available USV that relies on sea surface waves to produce forward thrust, making it suitable for sustained operations at sea without human assistance. Along with the instrumentation needed for navigating autonomously, the vehicle carries several scientific payload integrated on the USVs hull and keel (between 25 and 50 cm approximately below the waterline) that collects information about a wide range of environmental variables. Among these, we had an Eco Triplet sensor (Wet Labs, Oregon, USA) to measure \( FChla \) \( (\lambda_{ex}=470 \text{ nm}, \lambda_{em}=695 \text{ nm}) \), turbidity \( (\lambda=700 \text{ nm}) \) and fluorescence of colored dissolved organic matter \( (CDOM, \lambda_{ex}=370 \text{ nm}, \lambda_{em}=460 \text{ nm}) \). A manufacturer calibration factor converted the units of \( FChla \) to \( [Chla] \) \( (\text{mg m}^{-3}) \), \( CDOM \) to ppb and turbidity to Nephelometric Turbidity Units (NTU). In addition, the USV was equipped with a Seabird CTD SBE 49 (sampling rate of 16 Hz) for measurements of temperature and salinity and an oxygen Optode 4835 (Aanderaa) for oxygen concentration \( (\mu\text{M}, \text{later converted to mg L}^{-1}) \). Finally, a weather station (Airmar 220WX) for measurements of wind speed was located on the mast of the USV. The USV was deployed from the Mausund field station (located north of Frøya island, in the south-western part of Frohavet, Fig. 1) on 12\textsuperscript{th} April 2022 and navigated in Frohavet until 28\textsuperscript{th} April 2022. The log files of each sensor were converted to CSV format and merged in Python. Data was binned for every minute.

2.4 Non-photochemical quenching correction

\textit{In vivo} (in situ) \( FChla \) is commonly used as a proxy for phytoplankton biomass. However, when phytoplankton cells are usually exposed to high irradiance (particularly around...
noon), excess energy is dissipated as heat, reducing the \( FChla \) signal in the water (Travers-Smith et al. 2021). This photophysiological process is called non-photochemical quenching (\( NPQ \)) (reviewed by Brunet et al., 2011). To visualize the overall trend of corrected \( FChla \), the beginning of each \( NPQ \)-induced trough was connected linearly to the end of the trough, resulting in a straight line over the period affect by \( NPQ \). This method excludes the \( FChla \) suppressed by \( NPQ \) and ignores small variability of \( FChla \) during the day, however, it suits well to show general trends of bloom dynamics (before, peak and post-bloom) in April 2022.

2.5 Satellite observations

Sentinel-3 images from OLCI (Ocean and Land Colour Instrument) sensor (multispectral imager) are used to provide an overview of the sampling region, and to assess whether the USV is observing spatial or temporal variations in the \( FChla \). To determine the daily pattern of \( Chla \), all the Sentinel-3 \( Chla \) maps which contain the target region during the day were downloaded and merged. The images are resampled to the same spatial grid and averaged. Pixels which displayed land or clouds were excluded from the averaging process.

2.6 Mixed Layer Depth

Mixed layer depth was calculated from data from SINMOD, a 3D ocean model system. The model has been established for the coastal region outside mid-Norway with a high spatial resolution (800m). SINMOD's hydrodynamic component utilizes the primitive Navier-Stokes equations to calculate ocean properties such as water current, velocity, water temperature, and...
pressure (see Slagstad & McClimans, 2005 for more details on the hydrodynamic module). The model is established on a \( z/z^* \)-grid with fixed horizontal grid size and nesting for high spatial resolution. The North Atlantic and Arctic region are modeled with a 20 km resolution, which produces boundary conditions for a higher resolution configuration of 4 km horizontal grid size for the Nordic Seas and further to 800 m grid size for the coastal region outside Mid-Norway. The 20 km model uses specified boundary conditions, including 12 tidal components at open boundaries, with data imported from the TPXO tidal model for global ocean tides. Interpolated ERA5 atmospheric data from ECMWF (for more details see Hersbach et al. (2020)) is used to force the ocean model domain, including 3 hourly wind forcing, air pressure, and daily air temperature, humidity, and cloud cover to calculate heat exchange. Norwegian freshwater discharges from rivers and land are applied using data from simulations by the Norwegian Water Resources and Energy Directorate with a version of the HBV-model (Beldring et al., 2003), while historic data from SMHI Hype model data is used for other European rivers (https://hypeweb.smhi.se/). For more information, refer to Hersbach et al. (2020). Mixed layer depth is calculated from the SINMOD output as the depth at which the density gradient exceeds 0.01 kg m\(^{-1}\).

3 Results

3.1 Mooring buoy data

Integrated daily irradiance above water from HOBO light loggers (converted from klux to \( \mu \)mol photons m\(^{-2}\) s\(^{-1}\), see methods) gradually increased from mid-February to mid-June, showing peak in values (up to \( 2 \times 10^4 \) \( \mu \)mol photons m\(^{-2}\) s\(^{-1}\)) from early April until early May (Fig. 2a).
This suggests a period of consistent clear and sunny skies in April for at least 2 weeks. Average wind speed varied in the region of Frohavet from February until mid-June (Fig. 2b). Average wind speed was particularly strong (up to 20 m s⁻¹) during March and early April (Fig. 2b). From mid-April until late April (time when the USV AutoNaut was in Frohavet, Fig. 2e), average wind speed was relatively weak for several days (< 5 m s⁻¹) compared to March. Concomitantly, seawater temperature from a buoy (~3 m deep) located near the coast of Frøya island (Fig. 1) gradually increased from early April until late June and shortly increased from ~ 6 to 8°C in mid-April (Fig 2c). Chlorophyll a concentrations (FChlaBuoy) and turbidity from the buoy station near Frøya island (Fig. 1) gradually increased from mid-March and peaked from mid to late April. The spring bloom (March-June) consisted of multiple peaks (Fig. 2d) - a short peak in late March where the haptophyte Phaeocystis sp. dominate the bloom and a second long peak during April where diatom Skeletonema spp. is the dominant genus (Table S1. Supplementary material). The USV AutoNaut was located in Frohavet before, during and after the *Skeletonema* bloom in April (Fig. 2e), capturing the temporal and spatial dynamics of the bloom.
Figure 2 - Time series of environmental parameters and the spring phytoplankton bloom. a) integrated daily irradiance (µmol photons m\(^{-2}\) s\(^{-1}\)), b) average wind speed (m s\(^{-1}\)), c) temperature (°C), d) \textit{in vivo} chlorophyll (mg m\(^{-3}\)) and turbidity (FTU) from the stationary buoy from mid-February until mid-June 2022 and e) uncorrected \textit{in vivo} chlorophyll from the AutoNaut from April 11\(^{th}\) – April 28\(^{th}\). Grey box in b) and c) represents lack of data due to malfunctioning of the instrument. For d) and e) dot represent the median-calculated data from seven consecutive runs and line represents the smoothing parameter (\textit{rloess} method in Matlab).
3.2 Daily variation of $FChla_{AUTO}$

$FChla_{AUTO}$ (mg m$^{-3}$) varied with time, with low values around 12$^{th}$ April (<1 mg m$^{-3}$), increasing gradually until 16$^{th}$ April, reaching maximum average values ~ 4 - 5 mg m$^{-3}$ and decreasing again on the 23$^{rd}$ – 24$^{th}$ April (average ~ 1 mg m$^{-3}$) (Fig. 2d). $FChla_{AUTO}$ (mg m$^{-3}$) varied also as a function of irradiance during the day cycle, showing low values when irradiance is the highest (around noon) (Fig. 3a). Such low $FChla_{AUTO}$ daylight values occurred due to $NPQ$. To correct for this values, linear interpolation of night $FChla_{AUTO}$ was used, to show the robust trends in [Chla] chlorophyll concentration before, during and after the bloom (Fig. 3b).
Figure 3: Daily and temporal variations of in situ chlorophyll a fluorescence ($F_{Chl\text{a}_{AUTO}}$ (mg m$^{-3}$)) and modelled irradiance. a) Time series and b) daily cycle of $F_{Chl\text{a}_{AUTO}}$ uncorrected (red) and corrected for non-photochemical quenching (green) from the USV AutoNaut and modelled daily irradiance (yellow) derived from 12th – 28th April 2022.
3.3 USV AutoNaut

The USV AutoNaut was present in surface waters of Frohavet from April 11\textsuperscript{th} – April 27\textsuperscript{th} (Fig. 4a). The USV departed from a small island, Mausund, north of Frøya island and moved towards the deep waters of Frohavet. The USV initially moved out of Mausund Island and northwards around 15\textsuperscript{th} April, along Froan archipelago, then east around 19\textsuperscript{th} April, then south (east of Frøya) on April 23\textsuperscript{rd}, completing its mission around the center, deep waters of Frohavet (Fig. 4a).

Corrected $F\text{Chl}a_{\text{AUTO}}$ (mg m\textsuperscript{-3}) gradually increased from April 11\textsuperscript{th}, reaching its peak (up to 5.5 mg m\textsuperscript{-3}) on ~ April 16\textsuperscript{th} until ~ April 22\textsuperscript{nd} when it abruptly declined, and reaching low values (< 2 mg m\textsuperscript{-3}) (Fig. 4b). Average turbidity values were lower than 0.2 (NTU) from April 11\textsuperscript{th} – April 12\textsuperscript{th}, slightly increasing during the period of the bloom (average > 0.2 NTU). Turbidity values were less ‘noisy’ from 14\textsuperscript{th} - 20\textsuperscript{th} April and gradually declined until 23\textsuperscript{rd} April, becoming again noisier and around 0.2 NTU afterwards. Sea surface temperature (SST), colored dissolved organic matter (CDOM) and dissolved oxygen (DO) gradually increases from April 11\textsuperscript{th} until April 18\textsuperscript{th} (~ 6 - 9°C for SST, 1.1-2.2 ppb for CDOM and 9.7 - 13 mg L\textsuperscript{-1} for DO).

Concomitantly, salinity and average wind speed (m s\textsuperscript{-1}) decrease from 34 to 32 and from 10 m s\textsuperscript{-1} until 3 ms\textsuperscript{-1}, respectively. Salinity sharply increases from 32 to 33 and CDOM and SST abruptly decreases on April 19\textsuperscript{th}, from 2.1 to 1.2 ppb and 8.9-7.5, respectively. At the same period (particularly on April 20\textsuperscript{th}, wind speed peaks up, reaching > 10 m s\textsuperscript{-1}). From April 18\textsuperscript{th} onwards (until April 26\textsuperscript{th}), SST, CDOM, salinity and wind speed fluctuate. DO reach highest values on April 19\textsuperscript{th} and 20\textsuperscript{th} and sharply goes down to < 10 mgL\textsuperscript{-1} after April 23\textsuperscript{rd}. 
Figure 4- Track of the USV AutoNaut and the environmental parameters collected. a) Frohavet region and the track line of the USV AutoNaut from 11th – 28th April. Time series of b) corrected chlorophyll a fluorescence ($F_{\text{Chla}}^{\text{AUTO}}$ (mg m$^{-3}$)), c) turbidity (NTU), d) sea surface temperature (SST ($^\circ$C)), e) salinity, f) colored dissolved organic matter (CDOM (ppb)), g) dissolved oxygen (mg L$^{-1}$), and h) wind speed (m s$^{-1}$) from the USV AutoNaut.
3.4 Satellite images and USV AutoNaut track

To verify whether the bloom variability detected by the USV AutoNaut is temporal (e.g. start, peak and collapse) or spatial (patchiness), daily satellite images along with the USV tracks were analyzed together (Fig. 5). According to satellite images and, in alignment with the observations from the USV, the bloom started from ~ April 7th – 18th, peaked ~ April 21st, declined on April 24th, where the USV was confined in relatively low [Chla] regions (< 1 mg m\(^{-3}\)) and collapsed on April 26th (Fig. 5).

![Satellite images (Sentinel 3) of chlorophyll a concentrations (mg m\(^{-3}\)). Spatial and temporal variability of [Chla] in Frohavet region on April 7th, 14th, 18th, 21st, 24th and 26th. Note the tracking path of the USV AutoNaut for each day, during early (yellow) to late (red) hours.](image-url)
3.5 Correlation of USV AutoNaut parameters

The phytoplankton bloom observed as corrected $FChla_{AUTO}$ seemed, in general, not to be concentrated within a certain water mass, being widely present in waters with low and high salinity and temperature values (Fig. 6a and 6c). The phytoplankton bloom seemed to, rather, have a temporal trend, starting from 12-13$^{th}$ April and ending on 21$^{st}$ April. Salinity and CDOM presented a negative relationship, changing progressively in values in the early phase of the bloom (Fig. 6a and 6b). Temporally, the USV AutoNaut traveled waters with a wide range of salinity and temperature in the beginning of the mission, concentrating later in the center of Frohavet (after April 19$^{th}$ – salinities are between 32 and 33) (Fig. 6d). Lowest daily turbidity values had a positive relationship with DO and chlorophyll (Fig 6e and 6f). Waters with high dissolved oxygen levels (> 11 mg L$^{-1}$) had less variability (which coincided with a period of weak winds and high chlorophyll concentrations) (Fig. 4c and 4h).
Figure 6 - Correlation plots between parameters from the USV AutoNaut. Correlations between a,b) salinity and coloured dissolved organic matter (CDOM (ppb)), c,d) salinity and temperature (°C) and e,f) dissolved oxygen (mg L⁻¹) and turbidity (NTU) as function of FChla_{AUTO} (left) and time (right) from the USV AutoNaut.
Values of corrected $FChla_{AUTO}$ varied as a function of wind during the period that the USV AutoNaut was in Frohavet (Fig. 7). During a pre-bloom condition (~April 11th – 13th), average wind speed was variable (from 1-10 m s$^{-1}$), followed by a blooming period (> 2 mg m$^{-3}$), where corrected $FChla_{AUTO}$ values from the USV AutoNaut rapidly increase in a few days (~April 13th – 15th). During the blooming period average wind speed was low (< 6 m s$^{-1}$), while DO and turbidity were high (> 10 mg L$^{-1}$ for DO and > 0.2 NTU for turbidity) (Fig 7c,d). After this period, here referred as ‘transitional period’, winds started to pick up (average speed from 7 to 13 m s$^{-1}$), while chlorophyll concentration and turbidity were still high (> 4 mg m$^{-3}$ for corrected $FChla_{AUTO}$ and 0.25 NTU for turbidity) (Fig. 7). The transitional period was followed by a post-bloom period, where chlorophyll values were low (< 2 mg m$^{-3}$) but average winds were still high (from 5 – 13 m s$^{-1}$) (Fig. 7b).
Figure 7- Correlation plots of parameters from the USV AutoNaut. Correlation plots between a) year day and corrected chlorophyll fluorescence ($FChla_{AUTO}$ (mg m$^{-3}$)), b) wind speed (m s$^{-1}$) and corrected chlorophyll fluorescence ($FChla_{AUTO}$ (mg m$^{-3}$)), c) wind speed (m s$^{-1}$) and dissolved oxygen (mg L$^{-1}$) and d) wind speed (m s$^{-1}$) and turbidity (NTU).
3.6 Discrete water sampling and modelled mixed layer depth

Nitrate concentrations from discrete water samples collected at the coast of Frøya, where the buoy is located (Fig. 1), showed an overall continue decline from mid-February until mid-June with pulses of nutrient occurring on April 5th and May 4th (6 and 4 µM, respectively, Fig. 8a).

Values of [Chla_{in-vitro}] increased with time, with a decline on May 4th (< 2 µg L^{-1}, Fig. 8b), which coincided with the post bloom period observed after the USV AutoNaut was in the water.

Modelled mixed layer depth was shallow (< 15 m), particularly during the period of bloom development, when the USV AutoNaut was in the water (Fig. 8c).
Figure 8- Nitrate, *in vitro* chlorophyll *a* concentrations and mixed layer depth as a function of time. Time series of a) nitrate concentrations (µM) and b) *in-vitro* chlorophyll *a* from discrete water samples collected at 3 m depth from near Frøya island (µg L⁻¹). c) Modelled average mixed layer depth (MLD) from 31st March – May 13th derived from SINMOD simulations. Location of Frøya and regions of modelled MLD simulation is shown in Figure 1 (circle symbol).
4 Discussion

4.1 Non-photochemical quenching

In vivo \( FCh\alpha \) signal varied widely in this study as a function of daily irradiance. Non-photochemical quenching clearly affected the \( FChl_{\text{AUTO}} \) signal during daytime, appearing low when irradiance is high (peak at noon), while being stable during nighttime. Methods for \( NPQ \) correction from fluorometers installed on mobile (e.g. gliders and BCG-Argo floats) and moored platforms (e.g. vertical profilers and buoys) have been established (Fragoso et al., 2021; Lucius et al., 2020; Xing et al., 2018). Each of these methods follows their own set of assumption, given that not all set of parameters are measured from distinct platforms. For semi-autonomous observations (e.g. USVs), interpolation of unaffected nighttime \( FCh\alpha \) signal has been applied in this and other studies to correct for \( NPQ \) (Scott et al. (2020). In Scott et al. (2020), daytime \( FCh\alpha \) from the USV Saildrone was corrected using the proportion of \( FCh\alpha \) to Volume Scattering Function (\( \beta \), 124°, 650 nm) from the night before and after the \( NPQ \) event and assumed that daytime \( \beta \) measurements are not influenced by \( NPQ \). As suggested by the authors, this method is only appropriate under a close examination of the types of water masses. That is because it assumes a consistent temporal and spatial distribution of factors that influences \( \beta \), such as detritus, sediments and phytoplankton. In our study, this method was not suitable due the noisy turbidity measurements (particularly when wind speed was high), suggesting the influence of air bubbles and particles, such as sediments and detritus in the backscattering signal. Although phytoplankton constitutes a significant portion of particles in productive waters of the coast of mid-Norway, other particles, including zooplankton, fecal pellets, sediments and detritus can be
highly heterogeneous in space and time, influencing the backscattering signal (Fragoso et al., 2019; Fragoso et al., 2021). Thus, for $F\text{Chl}_{\text{AUTO}}$ corrections in this study, daily measurements were based the percent reduction in $F\text{Chl}_{\text{AUTO}}$ by modelled irradiance. This method is only appropriate to observe daily trends in $F\text{Chl}_{\text{AUTO}}$, rather than sub-mesoscale patchiness of phytoplankton distributions occurring less than a day.

### 4.2 Phytoplankton bloom dynamics

The spring bloom (March-June) in Frohavet consisted of multiple peaks - a short one in late March dominated by the haptophyte *Phaeocystis*, a second long one (2 weeks) during April (where diatom *Skeletonema* spp. is the dominant) and a third ‘on-and-off’ bloom until late June dominated again by *Skeletonema*. Multiple biomass peaks composed of the same taxa (in this case *Skeletonema*) or assemblages of taxa are likely a response of the dynamic nature of this region. In these places, distinct stochastic drivers (nutrient pulse, a period of calm weather, heatwaves, grazing selection etc.) determine the timing of peaks over a short period of time (Type 4 blooms as described in Isles and Pomati, 2021). This means that for each of these blooms observed in during spring to summer in Frohavet, distinct abiotic (changes in nutrient and light conditions) and biotic factors (grazing pressure) might have shaped the intensity, composition and duration of those blooms.

The USV was in the water in April during the second long $F\text{Chl}_{\text{BUOY}}$ peak (2 weeks) and captured the temporal and spatial dynamics of *Skeletonema* bloom before, during and after its recession. During this period, a rise in $F\text{Chl}_{\text{AUTO}}$ from the USV AutoNaut occurred concomitantly with a rise in SST and [CDOM] as well as with a decrease in salinity values and
wind speed, suggesting that sunny skies, calm winds and warmer temperatures promoted snow
melt and high freshwater input from river run off along the coast. Thus, light was the
environmental driver that likely promoted this bloom, since several days of clear skies and
relatively calm winds shoaled the mixing layer after intense wind mixing and prolonged period
of low light conditions of Norwegian winter. In the North Atlantic, similar conditions were
observed where a dramatic increase in cellular division rates (net population growth rate from
0.02 to 0.08 divisions d\(^{-1}\)) over a short period of time (9 days) occurs as a consequence of the
rapid shoaling of the mixed layer during calm weather periods, consistent with Sverdrup’s
paradigm (Mignot et al., 2018). In Frohavet, \(FChla_{BUOY}\) started to accumulate since mid-March,
but it was not until mid-April that a proper bloom was observed, where concentrations changed
from 1 to 5 mg m\(^{-3}\) in 5 days.

While the spring bloom in this study developed exponentially with 5 days, the collapse of
the bloom was rather quick, 1-2 days. \textit{Skeletonema} sp. is an ubiquitous fast-growing diatom
(Lundsør et al., 2022), and it is possible that nutrient limitation after intense growth could have
caused the collapse of the bloom. However, due to the intermittent changes and dynamic
nature of weather conditions of the coast of mid-Norway, particularly from winter to spring
transition, it is likely that strong wind speed and deepening of the mixing layer (after 2 weeks of
calm weather) paused the bloom development. This could initially dilute the accumulated
biomass and consequently reduced the availability of light for the phytoplankton growth. Similar
conditions were observed in the Northwestern Mediterranean Sea, where subsequent storms and
vertical mixing due to the intermittent changing weather conditions from winter to spring cause
the collapse of spring blooms (Keerthi et al., 2021). In this study, the evidence of a storm surge
shown by the sudden increase in average wind speed and increased nutrient availability at the
surface in early May indicates that vertical mixing likely promoted the rapid decline of the bloom.

Zooplankton abundance and top-down pressure is evident in the coast of mid-Norway, particularly during summer (Fragoso et al., 2022). Although light might have induced phytoplankton cellular division to optimum levels, slight lags (few days) in zooplankton grazing might have been another reason why phytoplankton accumulation reached a peak (3-4 days), where grazing rates outbalanced phytoplankton division and growth. This suggests that loss processes, such as grazing, can also be rather fast, highlighting the need of highly temporal and spatial-resolved measurements in dynamic regions. The copepod *Calanus finmarchicus* is the dominant mesozooplankton species in the Norwegian Sea and abundance has strongly been correlated with chlorophyll *a* concentration, suggesting tight coupling in other regions of the coast of Norway (Dong et al., 2022). Microzooplankton, such as ciliates and heterotrophic dinoflagellates, have a short generational time and high rates of predation, where slight lags in the response of these predators might have allowed for the positive accumulation rates during the initial state of the bloom (Mojica et al., 2021). Thus, it is likely that grazing might have slowed down further accumulation of phytoplankton biomass ([Chl *a]*) and bloom development, particularly in shallow mixed layers, which favors predator-prey encounter rates. Although the short-scale (few days) mismatch between phytoplankton and zooplankton abundances might have some influence in the development and collapse of the bloom, it is still likely that increase in average wind speed was the main obvious cause, given the fast (1-2 days) decline in chlorophyll concentrations from 5 to 1 mg m$^{-3}$. 
4.3 Submesoscale patchiness

High frequency-resolved mobile platforms such as the USV AutoNaut is a great tool to examine the sub-mesoscale variability of water masses, revealing the patchiness of the system (Dallolio et al., 2021). The wide range in salinity (31.5 - 34°C), temperature (6 - 9°C) and CDOM (1 - 2.5 ppb) reveals that the USV AutoNaut travelled through many distinct water masses, some with more or less influence of riverine input from Trondheimsfjord. Satellite images revealed that phytoplankton spatial distribution in Frohavet is highly patchy over the bloom period, but temporal changes, such as the start ~ April 7th, peak on April 21st, suppress on April 24th and collapse on April 26th were more prominent. The phytoplankton bloom was patchy, particularly on April 24th but did not appear to be confined to a certain water mass, rather transitioning in time and associated to wind conditions (low wind speed - accumulation and high wind speed – disruption of the bloom). This suggests that in spite of some degree of spatial variability observed in environmental factors (salinity and temperature, for example), the formation and decline of the bloom (from <1 to 6 mg m⁻³) was rather temporal due the fast changes in the environment (increase of wind strength).

5 Conclusions

Here we showed the detailed dynamics of a phytoplankton spring bloom in a complex productive region of the coast of Norway using an integrative observational approach. We observed a rapid
(5 days) bloom development (from 1 to 5 mg m$^{-3}$) dominated by the diatom *Skeletonema* occurring in spells of ‘good weather’, meaning few days of sunny, clear skies and weak winds in the middle of ‘stormy spring’, typical of high latitudinal regions. The collapse of this bloom was even faster, occurring in 1-2 days, concomitant with increase in wind speed, suggesting the strong influence of environmental conditions in the spring bloom.

Integrative approaches using of multiple ocean observation platforms (referred as the observational pyramid in Williamson et al., 2023) is essential to capture the short-term changes of phytoplankton in space and time. As climate continues to change, fluctuations in the environmental conditions (e.g. storm, floods, heatwaves) will likely become more and more frequent, and thus, the response of plankton communities, will likely become more extreme. Therefore, the combination of sensor-based technology and traditional methods for validation and monitoring of the ocean is fundamental to understand of the interlink and tipping points of phytoplankton dynamics to multiple environmental stressors related to climate change.

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Open Research

Our observational data of the parameters measured with the AutoNaut in Frohavet are available at 10.5281/zenodo.8283108.

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